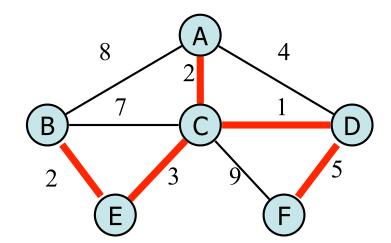
Today's announcements:

MP7 available. Due 12/6, 11:59p.

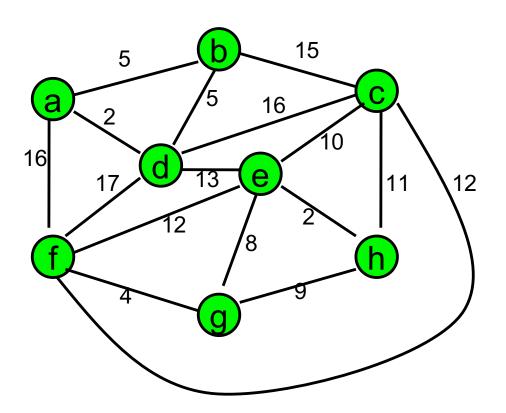
Exam5: 12/4-12/7, CBTF. Final: 12/8on, CBTF.

Minimum Spanning Tree Algorithms:

- •Input: connected, undirected graph G with unconstrained edge weights
- Output: a graph G' with the following characteristics -
 - •G' is a spanning subgraph of G
 - •G' is connected and acyclic (a tree)
 - •G' has minimal total weight among all such spanning trees -

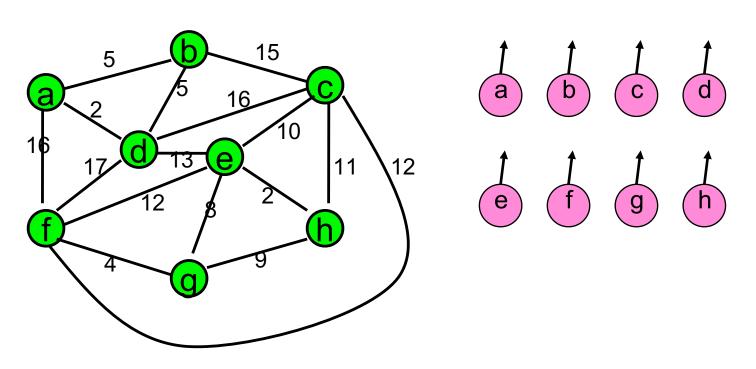


Kruskal's Algorithm



(a,d)
(e,h)
(f,g)
(a,b)
(b,d)
(g,e)
(g,h)
(e,c)
(c,h)
(e,f)
(f,c)
(d,e)
(b,c)
(c,d)
(a,f)
(d,f)

Kruskal's Algorithm (1956)



(a,d)

(e,h)

(f,g)

(a,b)

(b,d)

(g,e)

(g,h)

(e,c)

(c,h)

(e,f)

(f,c)

(d,e)

(b,c)

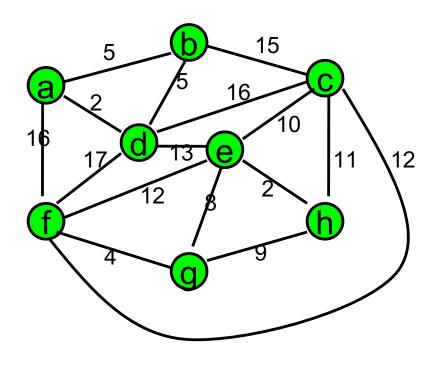
(c,d)

(a,f)

(d,f)

- 1. Initialize graph T whose purpose is to be our output. Let it consist of all n vertices and no edges.
- 2. Initialize a disjoint sets structure where each vertex is represented by a set.
- 3. RemoveMin from PQ. If that edge connects 2 vertices from different sets, add the edge to T and take Union of the vertices' two sets, otherwise do nothing. Repeat until _____ edges are added to T.

Kruskal's Algorithm - preanalysis

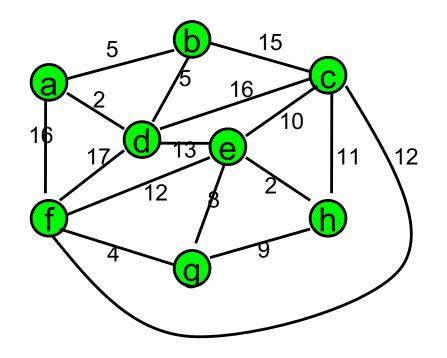


Priority Queue:	Неар	Sorted Array
To build		
Each removeMin		

Algorithm KruskalMST(G) disjointSets forest; for each vertex v in V do forest.makeSet(v); priorityQueue Q; Insert edges into **Q**, keyed by weights *graph* T = (V,E) with $E = \emptyset$; while *T* has fewer than *n*-1 edges do edge e = Q.removeMin()Let u, v be the endpoints of e if $forest.find(v) \neq forest.find(u)$ then Add edge e to Eforest.smartUnion (forest.find(v),forest.find(u))

return T

Kruskal's Algorithm - analysis



Algorithm *KruskalMST(G)*

```
disjointSets forest;
for each vertex v in V do
  forest.makeSet(v);
```

priorityQueue Q; Insert edges into Q, keyed by weights

```
graph T = (V,E) with E = \emptyset;
```

while T has fewer than n-1 edges do
 edge e = Q.removeMin()
 Let u, v be the endpoints of e
 if forest.find(v) ≠ forest.find(u) then
 Add edge e to E
 forest.smartUnion
 (forest.find(v),forest.find(u))

return T

Priority Queue:	Total Running time:
Heap	
Sorted Array	

Prim's algorithms (1957) is based on the Partition Property:

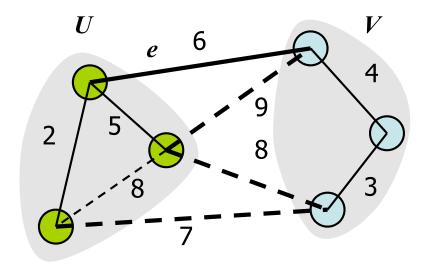
Consider a partition of the vertices of G into subsets U and V.

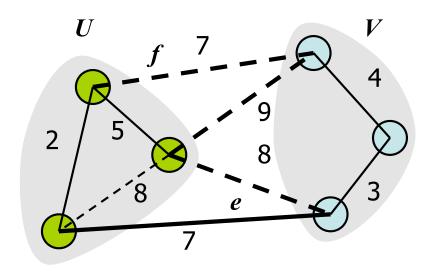
Let e be an edge of minimum weight across the partition.

Then e is part of some minimum spanning tree.

Proof:

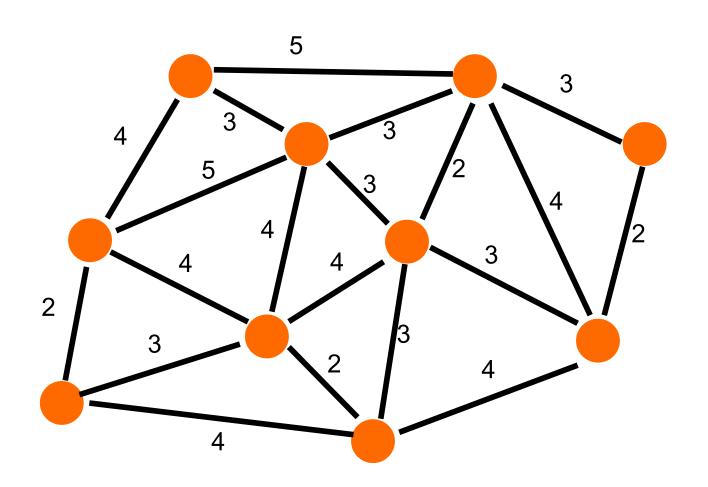
See cs374





MST - minimum total weight spanning tree

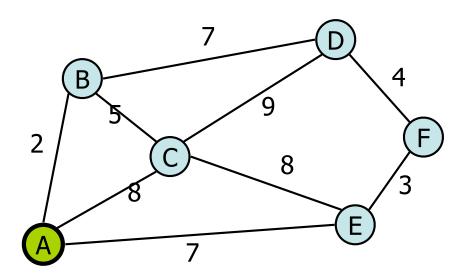
Theorem suggests an algorithm...



Example of Prim's algorithm -

Initialize structure:

- 1. For all v, d[v] ="infinity", p[v] =null
- 2. Initialize source: d[s] = 0
- 3. Initialize priority (min) queue
- 4. Initialize set of labeled vertices to ∅.



Example of Prim's algorithm -

Initialize structure:

- 1. For all v, d[v] = "infinity", p[v] = null
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- 4. Initialize set of labeled vertices to ∅.

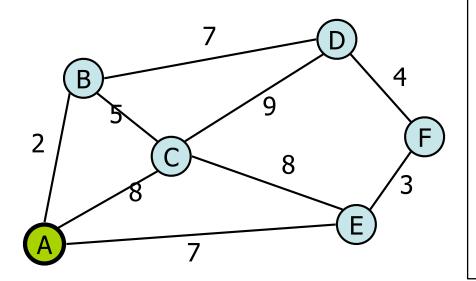
Repeat these steps n times:

- Find & remove minimum d[] unlabelled vertex: v
- Label vertex v
- For all unlabelled neighbors w of v,

If
$$cost(v,w) < d[w]$$

$$d[w] = cost(v,w)$$

$$p[w] = v$$



Prim's Algorithm (undirected graph with unconstrained edge weights):

Initialize structure:

- 1. For all v, d[v] ="infinity", p[v] =null
- 2. Initialize source: d[s] = 0
- 3. Initialize priority (min) queue
- Initialize set of labeled vertices to ∅.

Repeat these steps n times:

- Remove minimum d[] unlabeled vertex: v
- Label vertex v (set a flag)
- For all unlabeled neighbors w of v,

If
$$cost(v,w) < d[w]$$

$$d[w] = cost(v,w)$$

$$p[w] = v$$

	adj mtx	adj list
heap	O(n ² + m log n)	O(n log n + m log n)
Unsorted array	O(n²)	O(n²)

Which is best?

Depends on density of the graph:

Sparse

Dense